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~~55866-1. PROBLEM SOLUTIONS.~~

~~SOLUTIONS TO CHAPTER 1.~~

~~1.5 Linearization of the valve shows that~~

$$v=4v_3 \quad u.$$

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$$D(q-1)A(q-1)[T(t) - \hat{T}(t+1)]$$

(3.161) and the parameter adaptation algorithm satisfying the passivity condition will take the form: $\hat{T}(t+1) = \hat{T}(t) + F(t) - \hat{T}(t+1)$ (3.162)

The equivalent feedback representation associated with the output error predictor using the above PAA is shown in Fig. 3.9.

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